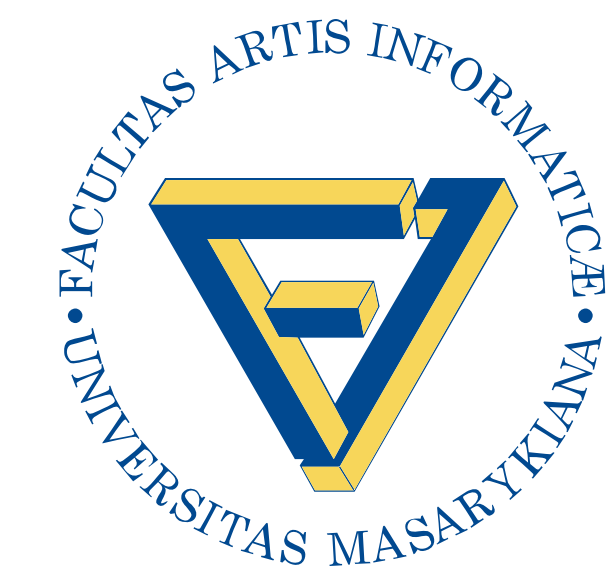


Regstar: Efficient Strategy Synthesis for Adversarial Patrolling Games

David Klaška, Antonín Kučera, Vít Musil, and Vojtěch Řehák

Faculty of Informatics, Masaryk University, Brno, Czech Republic



Abstract

- An efficient strategy synthesis method applicable to adversarial patrolling problems with **long distances** among targets and possibly **imperfect intrusion detection**.
- Experimentally evaluated that it is applicable to **real-world patrolling** graphs of reasonable sizes.
- Proof that **regular** (finite-memory) Defender's strategies are **arbitrarily close** to the power of general strategies.

Patrolling Games

Attacker



- aims to proceed attack
- attack takes time
- knows patroller(s) position and strategy

Targets



- parameters
- level of importance
 - attack length
 - visibility of attack

Patroller



- visits targets
- aims to disturb attacks
- knows nothing about attacker

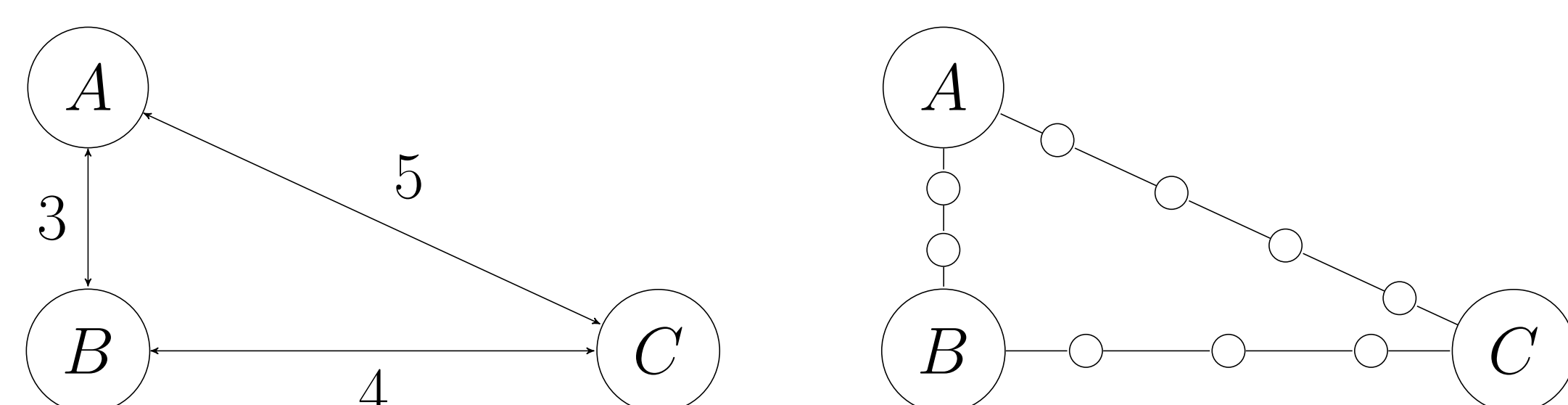
The goal is to find the best (randomized) strategy for the patroller.

Other Target Parameters

- vertices (targets) may have variable attack durations
- vertices (targets) may have variable importances
- **edges (distances) may have variable lengths**

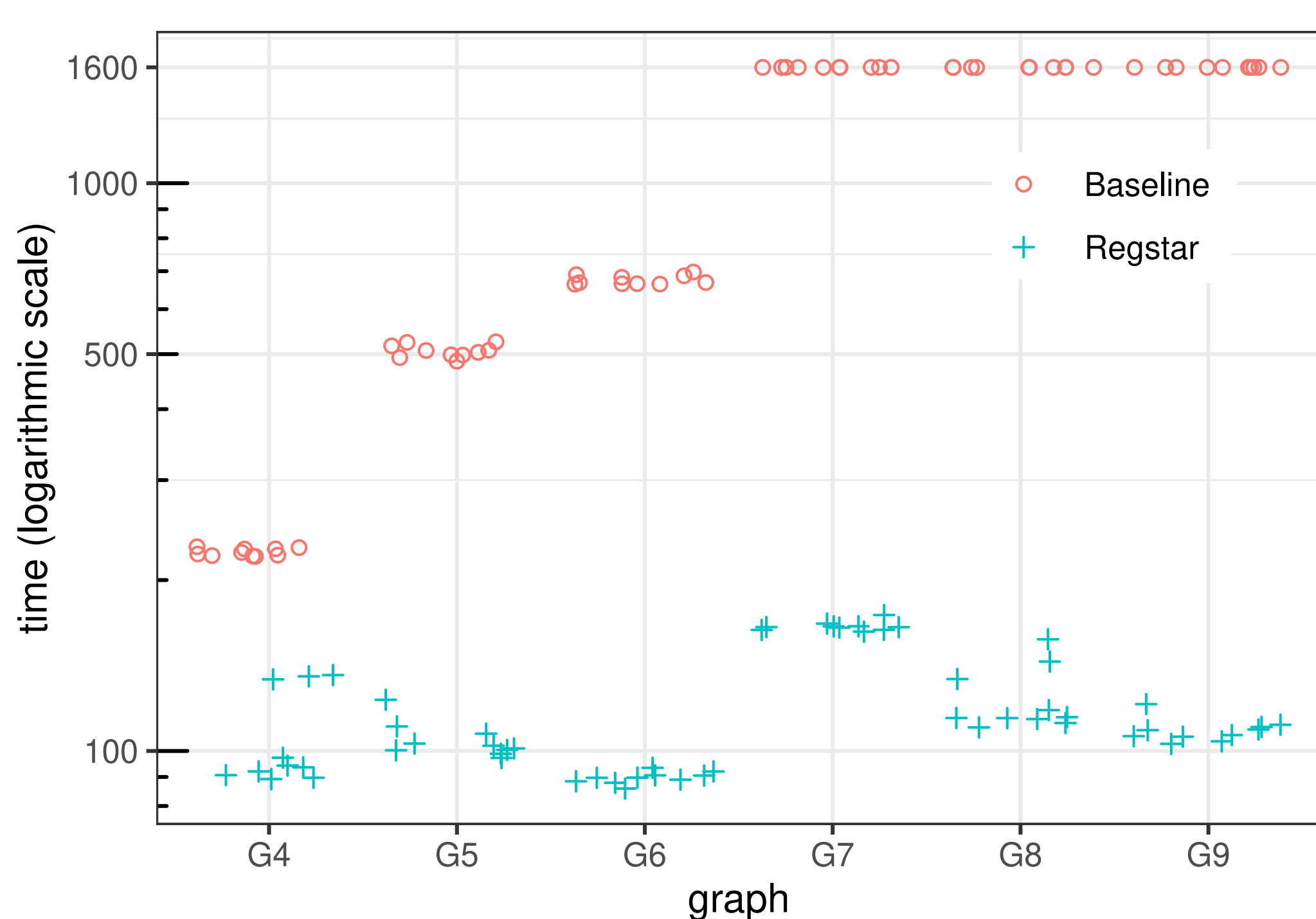
Variable Length of Edges

Contrary to the previous approach [1] using auxiliary vertices,



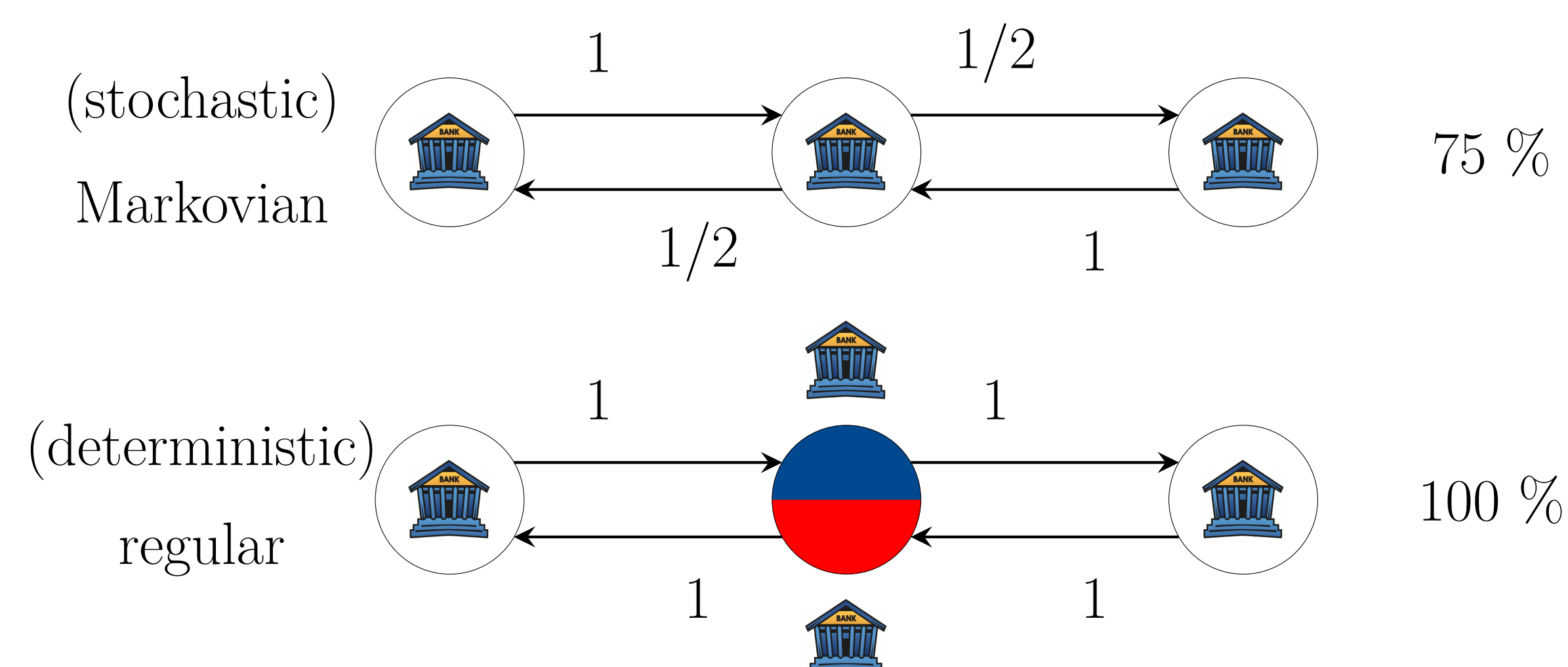
we come up with Regstar:

- based on **gradient descent**
- can deal with **imperfect detection**
- partly similar to Dijkstra's algorithm, but more **involved**
- i.e., **fast algorithm** for strategy synthesis



Types of Strategies

- type of general strategy is $\mathbf{V}^* \rightarrow \Delta(V)$
- not finitely representable
- Markovian (memoryless, positional) strategy: $\mathbf{V} \rightarrow \Delta(V)$
- k -Markovian strategy: $\mathbf{V}^k \rightarrow \Delta(V)$ for a fixed $k \in \mathbb{N}$
- regular strategy: $\mathbf{V} \times \mathbf{M} \rightarrow \Delta(V \times M)$ for a fixed **finite set** M



Which type of strategies is sufficient?

	ϵ -optimal	optimal
Markovian	NO	NO
k -Markovian	NO?	NO
regular	YES	YES?

Real-word Example: Montreal ATMs



On the graph of Montreal ATMs, we study the impact of the **memory size** on the quality of the synthesized strategy and the execution time of Regstar. $m = 1$ stands for positional strategy.

m	Val_{best}	Val_{avg}	# of iterations	time [s]
1	64	57 ± 3	280 ± 30	5 ± 1
2	75	70 ± 2	684 ± 41	79 ± 8
3	80	77 ± 2	1045 ± 60	360 ± 58
4	81	79 ± 1	1346 ± 75	1250 ± 196

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References

[1] Klaška et al. Automatic synthesis of efficient regular strategies in adversarial patrolling games. *AAMAS 2018*.